

Imagery Support Data (ISD) Documentation

v. 1.1.2



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1 Introduction

This document describes the Image Support Data (ISD) format for DigitalGlobe Imagery products. These products are available in a variety of product types, and contain different ISD depending on the type of the product. This document describes the ISD, overall structure of files and specifies the data content and format of individual fields for the following DigitalGlobe product types:

- Basic Products
- Stereo Products
- Standard Products
- Orthorectified Products
- Digital Elevation Model Products

This document also presents some technical information to explain the significance of the data.

The term "image" in this document often refers to a general two-dimensional image product, including a Digital Elevation Model (DEM) or another form of height model, as well as an image in the stricter sense. The context and the use of specific product type names should make it clear which meaning is intended.



2 Image Support Data

All Imagery Products are delivered with a set of metadata files called Image Support Data (ISD). The number and types of files delivered varies depending on the product ordered. The ISD files can be viewed as a collection point for all useful ancillary data. Table 2.1 lists the Image Support Data files that are delivered with each product type.

FILE NAME	EXTENSION	BASIC IMAGERY	STANDARD IMAGERY	ORTHORECTIFIED IMAGERY				
Delivery-Level ISD	Delivery-Level ISD							
Top-Level Index (Readme) File	.TXT	XX	XX	XX				
Top-Level Index (XML) File	.XML	XX	xx	XX				
Layout File	.JPG	XX	xx	XX				
Geographic Location Map Files	.shx, .shp, .dbf	XX	XX	XX				
Manifest File	.MAN	FTP only	FTP only	FTP only				
End of Transfer File	.ТХТ	FTP only	FTP only	FTP only				
Product Component-Level	ISD							
Product Component Index (Subdirectory Readme) File	.TXT	XX	XX	XX				
License File	.ТХТ	xx	xx	XX				
Image Metadata File	.IMD	xx	xx	XX				
Product Browse File	.JPG	xx	xx	XX				
Tile Map File	.TIL	xx	xx	XX				
Attitude File ¹	.ATT	xx						
Ephemeris File	.EPH	xx						
Geometric Calibration File	.GEO	xx						
RPC00B File	.RPB	XX	xx					
XML File	.XML	XX	xx	XX				

Table 2.1	Image Support	: Data (ISD) Files	Delivered by	Product Type
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¹ For users of Basic products, refer to *DigitalGlobe Imagery Support Data (ISD) Supplemental Documentation for Basic Products* for information regarding the .ATT, .EPH, and .GEO.



FILE NAME	EXTENSION	BASIC IMAGERY	STANDARD IMAGERY	ORTHORECTIFIED IMAGERY
Stereo Data File	.STE	xx	xx	

2.1 ISD File Description

Products include Image Support Data (ISD) at two levels: one set of Delivery ISD, and one set of Product Component ISD for each product option ordered. The number of product components depends on the layout of the order polygon with respect to scene or strip boundaries. If the order polygon is entirely contained within a single scene or strip, then only one product component will be delivered. If an order polygon crosses strip or scene boundaries, then the imagery product will be divided into multiple product components. Product options include panchromatic, multispectral, or pan-sharpened.

The Delivery ISD (one set per delivery) consists of:

- **Top-Level Index (Readme) File.** This file contains a list of names of the product files and the ISD files, along with copyright information for the entire product delivery.
- Top-Level Index XML File. This file contains the same information as the Top Level Index (README) file but in XML format.
- Layout File. This file spatially illustrates how the delivery order is spread out across the media including product and order polygon extents. The map includes volume and product labels. The file is in the standard JPEG format. Media volume information is not included for electronic deliveries.
- **Geographic Location Map Files.** These files spatially illustrate the product layout in a similar way to the layout file except in shapefile format. The files represent the order polygon, strip boundaries, product boundaries, and tile boundaries.
- Manifest File. The manifest file is included with electronic (FTP) deliveries only. The file contains the directory listing of the files delivered with the product.
- End of Transfer File. The end of transfer file is included with electronic (FTP) deliveries only. The appearance of this file on the FTP site indicates that DigitalGlobe has completed transferring all product files. It is a zero length file.

The Product Component ISD (one set per product component option) consists of:

- **Product Component Index (Subdirectory Readme) File.** The README file provides copyright information and the names of the ISD files for a single product within a delivery.
- License File. The license file contains the text of the selected license.
- Image Metadata File. The image metadata file describes key attributes about the image product, including product level, corner coordinates, and projection information, and time of acquisition.
- Product Browse File. The product browse file is a JPEG compressed browse image of the delivered product.
- **Tile Map.** The tile map file assists the customer in determining what tile to ingest to look at a specific part of the order polygon.
- Attitude File. The attitude file includes the time of first data point, the number of points, and the interval between the points and attitude information.
- **Ephemeris File.** The ephemeris file includes the time of first data point, the number of points, and the interval between the points and ephemeris information.
- **Geometric Calibration File.** The geometric calibration file contains the standard photogrammetric parameters of a virtual camera that models the corresponding camera and optical system for Basic Imagery products.
- **RPCOOB File.** The RPCOOB file contains the RPC information, which can be used to rectify the image. This is a mathematical mapping from object space coordinates to image space coordinates.
- XML File. This file contains the same information as the combined README, Licensing, Image Metadata, Tile Map and RPC00B files, in XML format. For Basic Imagery Products, the attitude, ephemeris, and geometric calibration file are included as well.
- **Stereo File.** This file is provided with Stereo pairs. It identifies each image in the stereo pair and describes the stereo ground coverage and viewing geometry.

2.2 File Layout

This section describes the structure by which the Image Support Data (ISD) files are organized for delivery. Figure 2.1 displays the layout as it applies to delivery of imagery and ISD files for all media types. Product Level Directories are



identified with the product ID and a three-character descriptor: PAN for Panchromatic, MUL for Multispectral, PSH for Pansharpened, and MOS for Mosaicked products.



Figure 2.1 File Layout Diagram



3 General Format and Conventions

3.1 General File Format

Image Support Data (ISD) files are provided in the Parameter Value Language (PVL). The information in PVL format is provided in multiple files while the information in XML is provided in a single file. The information provided in PVL and XML are the same semantically but differ only in syntax.

3.2 PVL Format

Each tag consists of a variable length parameter name and a parameter value, in the form parameterName = value followed by a semi-colon. The value can be an integer (decimal, binary, octal, or hexadecimal), a floating-point number, a character string (one or more characters), a coordinate universal time (UTC), a set, or a list. The format for UTC time is YYYY-MM-DDThh:mm:ss.ddddddZ. Character strings values must be enclosed in double quotation marks. Sets are delimited by { }, and lists are delimited by (). Nested sets and lists are allowed. Comments in the file begin with a slash-asterisk (/*) and end with an asterisk-slash (*/).

Named groups begin with BEGIN_GROUP = GROUPNAME and end with END_GROUP = GROUPNAME. Nested groups are allowed. The end of a PVL module is indicated by the keyword END, followed by a semi-colon.

Only required fields need to be specified in the ISD files.

For an example of the PVL-formatted file, please see Appendix A: Example PVL-Format on page 55.

3.3 XML Format

All the information contained in the PVL ISD files is also provided in XML format. For an example of the possible XML formatted file, please see *Appendix B: Example XML Format* on page 58.

3.4 Coordinate Conventions

For geolocation purposes, Image Support Data (ISD), for all product types, references both image coordinates and earth coordinates as described in the following sections.

3.4.1 Earth Coordinates (E)

Earth coordinates are expressed relative to an earth-centered fixed (ECF) reference system that rotates with the earth. In particular, all ECF coordinates in ISD files are given in the WGS 84 reference system, including geocentric cartesian coordinates (X_E , Y_E , Z_E) and geodetic coordinates (latitude, longitude). The WGS 84 Z_E -axis points in the direction of the Conventional Terrestrial Pole (CTP); the X_E -axis lies along the intersection of the meridian plane and the CTP equator, pointing outward at Greenwich; the Y_E -axis completes the right-handed orthogonal coordinate system.





Figure 3.1 Earth Coordinate System

All heights are in meters with respect to the WGS 84 ellipsoid.

All easting and northing values in any of the ISD are specified in the projection determined by the datum and map projection fields in the image metadata file.

3.4.2 Image Coordinates

An image address is specified as a (column, row) pair. When the image is displayed, column numbers increase toward the right and row numbers increase in the downward direction. Address (0, 0) corresponds to the pixel displayed in the upper left corner. Adherence to these display conventions ensures that a displayed image will have the same sense as an aerial view of the ground—differing from an aerial view by a proper rotation.



Figure 3.2 Image Coordinate System



The detector in column 0 of a detector array produces the pixels in column 0 of the corresponding Basic image.

The ground location of a specific pixel in the image is the geolocation of the center of that pixel.

3.4.3 Time

All absolute times are in Coordinated Universal Time (UTC) in the format YYYY-MM-DDThh:mm:ss.ddddddZ.

Relative time offsets from a fixed absolute time are measured in seconds, unless specified otherwise.

An example of both absolute UTC time and relative time is the time-tagged line count (TLC) data in the image metadata file. The TLC data, which are pairs of line numbers and the associated exposure times, provide a way to accurately estimate the time of exposure of any line in the image. The first such timing event for an image is reported in the image metadata file as an absolute UTC time, but subsequent events are reported as time offsets, in seconds, relative to this initial time.



4 Delivery Level Support Data

4.1 Delivery Index (README) Contents

The Delivery Index contains a list of names of the product files and the Image Support Data (ISD) files, along with copyright information for the entire product delivery. The Delivery Index is found in a Top Level README file and a Top Level XML file delivered with each delivery, and each describes all of the files for all of the products delivered within that delivery. The README file and the XML file contain the same information. The Top Level README File is named for the 12-digit DigitalGlobe Order Item number and the 2-digit delivery increment, for example: 000000077583_01_README.TXT and 000000077583_01_README.XML. Table 4.1 defines the Top Level Delivery Index (README) contents.

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
version	Version of the ISD.	"20.0" to "99.99"	
copyrightText	Copyright and restricted use text.	"Use, duplication or disclosure by the government is subject to the restrictions as set forth in subparagraph (c)(1)(ii) of the Rights in Technical Data and Computer Software Clause contained in D.F.A.R.S. 252.227-7013, and subparagraphs (c)(1) and (2) of the Commercial Computer Software-Restricted Rights contained in 48 C.F.R. 52.227-19. Contractor/manufacturer is DigitalGlobe, Incorporated at 1601 Dry Creek Drive, Suite 260, Longmont, CO 80503-6493. Copyright YYYY DigitalGlobe Incorporated, Longmont CO USA 80503-6493 DigitalGlobe and the DigitalGlobe logo are trademarks of DigitalGlobe, Incorporated. The use and/or dissemination of this data and/or of any product in any way derived there from are restricted. Unauthorized use and/or dissemination is prohibited. DigitalGlobe WWW Reference: http://www.digitalglobe.com"	2nd paragraph Copyright YYYY DigitalGlobe Where yyyy is the current year
mediaCreationDate	Time of media creation.	YYYY-MM-DDThh:mm:ss.dddddZ	The time in this tag has precision to 6 decimal places.
orderNumber	12-digit DigitalGlobe Order Item number, underscore, and 2- digit delivery increment.	"nnnnnnnnnnn_mm" Example: "052265559010_01"	

Table 4.1	Top-Level	Delivery	Index	(README)	Contents	(ISDF.DEL.README)
10010 111	100 20101		mack		0011001100	(1001102211127.011127



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
fileList	A list of all files in the delivery including path directories.	Lists all filenames such as: GIS files Metadata files Product files	This field will vary depending on product type.
areaDesc	Customer supplied description of order. "Null" if no information supplied by the customer.	Example: "IS_05"	
dgOrderNo	DigitalGlobe Order Number.	Example: "052265559"	
dgOrderItemNo	12-digit DigitalGlobe Order Item Number.	Example: "05226559010"	
custOrderNo	Customer supplied order number. 'Null' if no information supplied by the customer.	Example: "IS_05"	
custOrderItemNo	Customer supplied order item number. 'Null' if no information supplied by the customer.	Example: "40005" "40009" "1" "Null"	
collectionStart	Date of first image acquisition.	YYYY-MM-DDThh:mm:ss.ddddddZ	
collectionStop	Date of final image acquisition.	YYYY-MM-DDThh:mm:ss.ddddddZ	
countryCode	Two letter country code of center point of order polygon.	Example: ""	Currently blank.
productScale	The NMAS mapping scale of Orthorectified Products.	Level 3A: "1:50,000" Level 3D: "1:12,000" Level 3E: "1:10,000" Level 3F: "1:5,000" Level 3G: "1:4,800" Level 3X: "Custom"	Only applicable to Orthorectified (level 3) products.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
numberOfLooks	Indicates whether this is a single product or a stereo pair.	"1" for single, "2" for stereo pair	
cloudCover	Estimate of the max cloud-covered fraction of the delivery. For mosaic products, this calculation is based on the intersection of the polygons contained in the MOSAIC_CLOSEDPOLY GONS shapefile with the cloud polygons associated with that part of the relevent input imagery.	0.000 to 1.000 Precision: 3 decimal places	-999.0 if not assessed
nwLat	Latitude of NW corner of the minimum bounding rectangle (MBR) of the order polygon.	Range: ± 90.0000000 Precision: 8 decimal places	
nwLong	Longitude of NW corner of the minimum bounding rectangle (MBR) of the order polygon.	Range: ± 180.0000000 Precision: 8 decimal places	
seLat	Latitude of SE corner of the minimum bounding rectangle (MBR) of the order polygon.	Range: ± 90.0000000 Precision: 8 decimal places	
seLong	Longitude of SE corner of the minimum bounding rectangle (MBR) of the order polygon.	Range: ± 180.0000000 Precision: 8 decimal places	



4.2 Delivery Layout File

The Layout file illustrates the following:

- Outline of the Product area (order polygon)
- Outline of the Product Component areas (product polygon)
- Distribution of the above areas on the delivery media

The Layout file is an image file in JPEG format, without any additional attributes. The information contained in this file is not duplicated in the Top Level XML file.

4.3 Delivery Geographic Location Map Files

Geographic Location Map files are similar to the Product Component Data files (Section 5) but in Shapefile format, projected to WGS84 Geographic (Lat/Lon). Table 4.2 through Table 4.7 define the Delivery Shapefiles contents. These product shapefiles are delivered as read/writable ASCII text files.

DigitalGlobe provides the following Geographic Location Map files with every delivery:

- **Strip or Substrip Area.** This file shows the vertices and boundaries of the strips or substrips used to generate the product, as well as the catalog ID for each of these areas. For example: 052265559010_01_STRIP_SHAPE.dbf
- **Product Area.** This file shows the vertices and boundaries of the complete product as ordered by the customer. For example: 052265559010 01 ORDER SHAPE.dbf
- Product Component Areas. This file shows the vertices and boundaries of the product components that make up the delivery, and the allocation of the product components to media. For example: 052265559010_01_PRODUCT_SHAPE.dbf
- **Product Subcomponent Areas.** This file shows the vertices, boundaries, name, and filename of each tile or sub-strip in the product components, as well as the product component to which each belongs. Example filename: 052265559010 01 TILE SHAPE.dbf
- **Product Pixel Area.** This file shows the vertices and boundaries of actual imagery pixels of the product components that make up the delivery (non-blackfill pixels.) In the Product Pixel area shapefile, the 12-digit DigitalGlobe Order Item number and the 2-digit delivery increment (SOLI) is pre-pended by an acquisition date-time of one of the contributing raw images along with a mnemonic that describes the product level as in the following example: 08JUL30153254-P2AS-052265559010_01_P001_PIXEL_SHAPE.dbf

For ortho-mosaic products, DigitalGlobe delivers an additional Geographic Location Map file for each product:

 Mosaic seamlines. This file shows the vertices and boundaries of each image strip that contributed to the generation of the mosaic. The Mosaic seamline <shapefile name> has the DigitalGlobe order's part ID (for example, P001) prepended. For example: 052270931010_01_P001_MOSAIC_CLOSEDPOLYGONS_SHAPE.dbf

Table 4.2 STRIP Shapefile Delivery Names and Attributes

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
stripDesc	Catalog ID corresponding with associated strip or substrip	Example: "10100100017C2400"	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
sunAzimuth	Azimuth angle of the sun measured from north clockwise, in degrees, at the time the strip or substrip was acquired.	Range: 0.0 – 360.0	Decimal precision may vary.
offNadir	The spacecraft elevation angle measured from nadir to the image center as seen from the spacecraft at the time the strip or substrip was acquired.	Range: ≥ 0.0	Decimal precision may vary.
acquisitio	Populated with the strip acquisition date-time.	Example: "2002-12- 29T15:58:08.626765Z"	

Table 4.3 ORDER Shapefile Delivery Names and Attributes

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
orderDesc	Item number corresponding with associated order polygon.	Example: "052265559010"	This is the 12-digit DigitalGlobe Order Item number. Required, if available.
custOrd	Optional order number supplied by the customer at time of order placement.	Example: "IS_46"	Only if customer has supplied order number. Required, if available.
custOrdItm	Optional order item number supplied by the customer at time of order placement.	Example: "40005"	Only if customer has supplied order item. Required, if available.
datum	The Datum in which the product was ordered.	"WE" (WGS84) "NAR" (NAD83) "NAS" (NAD27) "TOYM" (Toyko Mean) "GRS80" (GRS80)	Blank for Basic (1B) products.
projection	The projection in which the product was ordered.	"UTM" "State Plane Coordinates" "Japan RCS Coordinates" "Geographic (Lat/Long)"	Blank for Basic (1B) products.
createDate	Start date of product creation.	YYYY-MM-DDThh:mm:ss.dddddZ	



Table 4.4 TILE Shapefile Delivery Names and Attributes

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
tileName	Tile Name	If R or C ≤ 9: "RnCn" If R or C ≤ 99: "RnnCnn" If R or C ≤ 999: "RnnnCnnn" Examples: "R1C1" "R19C3" RegionTile Example: "iz_20071231_uncl_ci_ 322230n1153730w_imagery.tif"	Rows and Columns do not have to be of the same order of magnitude. For example: A tile of a mosaic with 6 columns and 15 rows would be displayed as: RnnCn
fileName	Name of the image file.	Example: "02JUN25001236-2AS_R1C1- 000000092184_01_P001.NTF"	
prodDesc	Unique product identifier	Example: "P001"	Required, if available.
volNum	Volume number of the media on which the tile is located.	Example: "Vol. 1"	

Table 4.5 PRODUCT Shapefile Delivery Names and Attributes

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
prodDesc	Unique product identifier	Example: "P001"	
volNum	Volume number of the media on which the tile is located.	Example: "Vol. 1-2"	
bandInfo	Defines type of spectral bands in product. (PanSharp, Multispectral, All Band, Panchromatic).	"PanSharp" "Multispectral" "All Band" "Panchromatic"	



Table 4.6 PIXEL Shapefile Delivery Names and Attributes

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
prodDesc	Unique product identifier	Example: "3AUG27021804-M2AS- 005357007010_01_P001_PIXEL_SHAPE"	
volNum	Volume number of the media on which the tile is located.	Example: "Vol. 1-2"	

Table 4.7 MOSAIC_CLOSEDPOLYGONS Shapefile Delivery Names and Attributes

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
imageIdStr	Imagery identifier	Example: "10100100012BEA00"	
acqDate	Imagery acquisition date	YYYY-MM-DDThh:mm:ss.ddddddZ	
gsd	Ground sample distance in meters	Range: 0.10000 – 100.00000 Precision: 5 decimal places	For validation, this range is 0.10000 to 100.00000.
horError	Requested product accuracy from the order	Range: 0.00000 – 15.44000 Precision: 5 decimal places	
cloudCover	Cloud cover percentage is calculated by intersecting the closed polygon with cloud polygons from the underlying image strips.	Range: 0.00000 to 100.00000 Precision: 5 decimal places	
offNadir	Angle from s/c to strip crosstract center.	Range: 0.00000 – 30.00000 Precision: 5 decimal places	Can be exceeded with reduced image quality.
scanAz	Image scan azimuth.	Examples for cardinal direction, but allow for all permutation including angles: "North-to-South" "South-to-North" "East-to-West" "West-to-East"	
scanDir	Image scan direction.	"Forward" "Reverse"	
collectAz	The orientation angle of the generated collection strip relative to true north.	Range: 0.00000 – 360.00000 Precision: 5 decimal places	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
collectEl	The collection elevation is the angle between the horizontal and the ray originating from the optical center to the point of incidence.	Range: 0.00000 – 90.00000 Precision: 5 decimal places	
sunAz	Sun azimuth.	Range: 0.00000 – 360.00000 Precision: 5 decimal places	
sunEl	Sun elevation.	Range: 0.00000 – 90.00000 Precision: 5 decimal places	
satellite	Satellite mnemonic	"QB02", "WV01", "WV02", "Aerial", "GE01", "WV03"	
prodDate	Production generation date	"YYYYMMDD"	
currDate	Production generation date	"YYYYMMDD"	
collDate	Date of image collection	"YYYYMMDD"	
absAcc	Product absolute accuracy	Range: 0.00000 – 100.00000 Precision: 5 decimal places	
absAccUnit	Absolute accuracy units	"Meters"	
relAcc	Product relative accuracy	Range: 0.00000 – 100.00000 Precision: 5 decimal places	
relAccUnit	Relative accuracy units	"Meters"	



5 Product Component-Level Support Data

5.1 Product Component Index (README)

The Product Component Index lists the names of the image, browse, and ISD files in each product component subdirectory of a delivery. Other ISD files may or may not be included in a delivery depending on the type of the products in the order. One Product Component Index is provided for each product component of each delivery within the product component subdirectory. Table 5.1 defines the Product Component Index contents.

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
copyrightText	Copyright and restricted use text	"(C) COPYRIGHT yyyy DigitalGlobe, Inc., Longmont CO USA 80503. DigitalGlobe and the DigitalGlobe logos are trademarks of DigitalGlobe, Inc. The use and/or dissemination of this data and/or of any product in any way derived there from are restricted. Unauthorized use and/or dissemination is prohibited."	Where <i>yyyy</i> is the current year
version	Version of the ISD	"20.0" to "99.99"	
intro	Introduction. General textual information about the product and file contents.	"Thank you for ordering from DigitalGlobe! This directory contains both an Imagery Product and the corresponding Image Support Data (ISD) files that fulfill your order. The naming convention for the image is <acquisition time="">-<product info="">-<product id>.<format extension="">"</format></product </product></acquisition>	
		BEGIN_GROUP=PROUDCT_1	
XMLFilename	Product Component XML file	"productname.XML"	
licenseTxtFilename	Licensing text file name	"BASE.TXT" "GROUP.TXT" "ENTERPRISE.TXT" "ENTERPRISE_PREM.TXT" "EDUCATIONAL.TXT" "DEMONSTRATION.TXT"	Predicated on license order parameter.
IMFFilename	Image metadata file name	"productname.IMD"	
ephemFilename	Ephemeris file name	"productname.EPH"	Only for Basic (1B) products.
attFilename	Attitude file name	"productname.ATT"	Only for Basic (1B) products.

Table 5.1 Product Component Index (README) Contents



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
tilFilename	Tile map file name	"productname.TIL"	
geoCalFilename	Geometric calibration file name	"productname.GEO"	Only for Basic (1B) products.
stereoFilename	Stereo file name	"productname.STE"	Only valid for stereo products
RPC00BFilename RPC00B file name "productname.RPB"		Not applicable to Orthorectified (level 3) products.	
END_GROUP=PRODUCT_1			
END;			



6 Image Metadata

6.1 Image Metadata Content

For ortho-mosaics, if an input image is not used as part of the final product, it will not be represented in the Image Metadata Data (IMD). All other input images will be represented in the IMD and will appear in order of their acquisition date-timestamp with the oldest image appearing first. The date-timestamp of the oldest image will be used as part of the product filenames.

The Image Metadata specifies the basic characteristics of an image or a DEM as specified in Table 6.1.

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
version	Version of the ISD	"20.0" to "99.99"	
generationTime	Time of file generation.	YYYY-MM- DDThh:mm:ss.ddddddZ	
productOrderId	Order Item ID of product	Example: "052270730010_01_P001"	Optional if product does not originate from DigitalGlobe or co- producer.
productCatalogID	ID for the corresponding record in DG's catalog. In multi-set products this would be the "group catalog id".	Example: "903001004AA74B00" "None"	"None" if catalog not kept in DigitalGlobe archive.
childCatalogID	ID for the corresponding record in DG's catalog (for multi-set products this would be the "child" or "subset" catalog id). In cases where children products do not have separate IMD files, this field may be repeated.	Example: "210001004AA74C00" "None"	Used only with multi-set products
imageDescriptor	This is a combination of product name and product type.	"Basic1B", "Standard2A", "ORStandard2A", "OrthoRectified3", "Stereo1B", "StereoOR2A", "DEM4"	

Table 6.1 Image Metadata Contents



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
productScale	This is the NMAS mapping scale of the Orthorectified Product	Values: Level 3A: "1:50,000" Level 3D: "1:12,000" Level 3E: "1:10,000" Level 3F: "1:5,000" Level 3G: "1:4,800" Level 3X: "Custom"	Only applicable to Orthorectified (level 3) products. For validation purposes, this shoudl be evaluted as a text string tha tis not bound by enumeration.
productAccuracy	Identifies the worst case CE90% in meters for the associated productScale.	Values: Level 3A: 25.40 Level 3D: 10.16 Level 3E: 8.47 Level 3F: 4.23 Level 3G: 4.06 "unavailable"	Only applicable to Orthorectified (level 3) products. For validation purposes, the actuals may range from 0.1 to 100.00.
RMSE2D	Two Dimensional Root Mean Square Error	Values: Level 3A: 15.44 Level 3D: 6.18 Level 3E: 5.15 Level 3F: 2.57 Level 3G: 2.47 Level 3X: 0.00 Precision: 2 decimal places	Only applicable for Orthorectified (level 3) products. Level 3X uses customer supplied data. For example, DEM(s), GCPs or both. Therefore, DG does not guarantee accuracy. For validation purposes, the actual values range from 0.1 to 99.00.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
bandld	Identifies the spectral band. "P" = Panchromatic, "Multi" = all VNIR Multi-spectral bands (4 for QB02,GE01 and 8 for WV02, WV03) "N" = Near-InfraRed "R" = Red "G" = Green "B" = Blue "RGB" = Red + Green + Blue "NRG" = Near-IR + Red + Green, "BGRN" = Blue + Green + Red + Near-IR RGB, NRG, and BGRN are pan- sharpened color images, stored at the panchromatic spatial resolution. For WorldView-2 and WorldView-3 there are also the following bands: "N2"=NIR2 "RE"=Red Edge "Y"=Yellow "C"=Coastal "MS1"=First 4 bands (N,R,G,B) "MS2"=Second 4 bands (N2,RE,Y,C) For a DEM, this field indicates the spectral band (Pan) used to create the product.	"P" "Multi" "N" "R" "G" "B" "RGB" "NRG" "BGRN" "NG" "BGRN" "N2" "RE" "Y" "C" "MS1" "MS2"	N2, RE, Y and C in any band combination are available for WorldView-2 and WorldView-3 only. For validation, this field is constrained by the following definition: A-Za-z0-9 (alphanumeric) plus '-' for up to 7 (1 to 7) characters.
panSharpenAlgorit hm	Identifies the algorithm used to create pan-sharpened products: UNB = University of New Brunswick	"UNB" "None"	
numRows	Number of rows.	1 – N	
numColumns	Number of columns.	1 – N	
productLevel	Product level that indicates the radiometric and geometric corrections for backward compatibility in terms of Product Type.	"LV1B", "LV2A", "LV3A", "LV3D", "LV3E", "LV3F", "LV3G", "LV3X", "LV4", "Stereo 1B", "Stereo 2A", "Stereo OR2A"	Refer to Table 4.5 for a definition of Product Levels.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
productType	Product type	"Basic", "Stereo", "Standard", "Ortho", "DEM"	
numberOfLooks	Indicates whether this is a single product or a stereo pair	Non-Stereo: 1 Stereo Pair: 2	
radiometricLevel	Options for radiometric correction.	"Corrected"	Not applicable for a DEM product.
radiometricEnhanc ement	Option for Color Correction and Contrast Enhancement	"DRA/Color" "DRA/Contrast" "Off"	Standard (level2), Stereo OR2A (level2A), and Orthorectified (level 3) Products only.
bitsPerPixel	The number of bits per pixel in the product image files. If the product is compressed, this value is the original bits per pixel, before compression. This value will be either 8 or 16, depending on the product. Note that this is the number of bits stored in the image file for each pixel value as opposed to the number of significant bits that define the pixel brightness value. That is, for a product which is delivered as 16 bits per pixel, only 11 bits define the brightness value of each pixel.	8 16	
restrictedAreaInter sect	Portions of the strip intersecting the restricted area have been modified to meet the allowable GSD.	"Yes"	This field will only be included if the strip intersects the restricted area and has been modified to meet the allowable GSD.
compressionType	The type of compression, if any, applied to the product imagery.	"None" "JPEG2000"	This field will not be included in Metadata products.
jpegProfileName	Name of the DigitalGlobe JPEG2000 profile applied.	"DG commercial 2.5" "DG commercial 12" "DG commercial 10:1" "DG commercial 8:1" "DG commercial 4:1"	Included only when the compression type is JPEG2000.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
The following group is N2,RE,Y,C) to different	repeated for each spectral band in the delivered tiate the band group names. In this group, latitud WGS 84 ellipsoid (HA	image product. The index b in the g les (Lat) and longitudes (Lon) are in E) are in meters.	roup name is one of (P,N,R,G,B, degrees and heights above the
	BEGIN_GROUP	P=BAND_b	
ULLon	Geodetic longitude of the upper left pixel of the image.	Range: ± 180.00000000 Precision: 8 decimal places	
ULLat	Geodetic latitude of the upper left pixel of the image.	Range: ± 90.00000000 Precision: 8 decimal places	
ULHAE	Height above the ellipse of the upper left pixel of the image.	Precision: 2 decimal places	
URLon	Geodetic longitude of the upper right pixel of the image.	Range: ± 180.00000000 Precision: 8 decimal places	
URLat	Geodetic latitude of the upper right pixel of the image.	Range: ± 90.00000000 Precision: 8 decimal places	
URHAE	Height above the ellipse of the upper right pixel of the image.	Precision: 2 decimal places	
LRLon	Geodetic longitude of the lower right pixel of the image.	Range: ± 180.00000000 Precision: 8 decimal places	
LRLat	Geodetic latitude of the lower right pixel of the image.	Range: ± 90.00000000 Precision: 8 decimal places	
LRHAE	Height above the ellipse of the lower right pixel of the image.	Precision: 2 decimal places	
LLLon	Geodetic longitude of the lower left pixel of the image.	Range: ± 180.00000000 Precision: 8 decimal places	
LLLat	Geodetic latitude of the lower left pixel of the image.	Range: ± 90.00000000 Precision: 8 decimal places	
LLHAE	Height above the ellipse of the lower left pixel of the image.	Precision: 2 decimal places	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
absCalFactor	The conversion factor, K _{nTDI} , that converts the relative radiance values in an image file into corresponding absolute radiance, measured in watts/sq m/ster. This is calibrated 6000 °K blackbody radiance, integrated over the appropriate spectral window.	Example: 6.447600e-02	-999 = "None" when radiometricEnhancement = "DRA".
effectiveBandwidt h	The effective bandwidth is associated with the absCalFactor and it's value is required to calculate top-of- atmosphere spectral radiance.	0.0000 to 1.0000 scientific notation	
TDILevel	Level of the time-delayed integration, as commanded to the spacecraft.	Values: PAN: 6, 8, 10, 13, 16, 18, 24, 32, 48, 56, 64 MS: 1, 3, 6, 10, 14, 18, 21, 24 GE01 Pan: 8, 16, 32, 48, 64 MS (mode 13/24): 3, 6, 10, 14, 18, 21, 24	1 only valid for QuickBird MS image.
	END_GROUP=	BAND_b	
outputFormat	External product format. GeoTIFF and NITF are image formats for Basic, Stereo, Standard and Orthorectified products. CIB is an image format for orthorectified 1:24,000 and 1:12,000, while DTED, USGS DEM, and ASCII DTM are digital elevation model formats for DEM products.	"GeoTIFF" "NITF20" "NITF21" "NITF21NCDRD" "TIFF" "CIB" "DTED" "USGS DEM" "ASCII DTM" "J2K" "GeoJP2" "GeoPDF" "MrSID" "RPF" "KIP" "IMG"	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
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The following group is repeated for each n = 1,...,numImagesInProduct. That is, for all images used to create the image product. For single image products (Basic) there is one .IMD file per source image or strip, so the group will appear only once for each product component. For multiple image products (Stereo, Standard, and Orthorectified), the following group will be repeated for each source image in the image product. The index "n" in the group name is a sequential number of the image used to produce the product (1,2,3,...,n) to differentiate the image group names. The image with the earliest aquisition time will be assigned n = 1, and incremented in ascending order.

BEGIN_GROUP=IMAGE_n			
satld	Satellite Id.	"QB02", "WV01", "WV02", "GE01", "WV03"	
mode	Sensor Mode.	"FullSwath", "CenterSwath"	Only "FullSwath" for QuickBird.
scanDirection	Sensor scan direction.	"Forward", "Reverse"	Only "Forward" for QuickBird
Catld	DigitalGlobe catalog Id for the raw data used in this product. For mosaics, only strips used in the mosaic creation should be listed. The catalog ids are ordered from earliest aquisition to latest.	Example: "1020010007AF7100"	For each sub-strip or area based product.
TLCTime	Absolute time of the first time-tagged line count record, used in the product component.	YYYY-MM- DDThh:mm:ss.ddddddZ	Only for Level 1B products.
numTLC	Number of time-tagged line count records in the TLCList used in the product component.	Range: ≥ 1	Only for Level 1B products.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
TLCList	List of time-tagged line count (TLC) records. Each TLC record consists of lineNumber (Short) timeOffset (Float) lineNumber is the image line number for a line in the product component. This number will be negative if the TLC record precedes the product component. timeOffset is the recorded time tag for this line, in seconds after TLCTime. The timeOffset will be negative if the image is in the reverse scan direction.	Example: ((-256, 0.000000) , (768, 0.148404), (N, N.nnnnn)) Precision: TLCTime will have 6 decimal places precision.	Only for Level 1B products.
firstLineTime	Exposure time for the first line in the strip used for the product component.	YYYY-MM- DDThh:mm:ss.ddddddZ	
avgLineRate	Average number of image lines exposed per second.	Precision: 2 decimal places	For Pan-Sharpened products, this will be equal to the average MS line rate.
exposureDuration	Duration of the exposure interval for each line.	Value: 1/avgLineRate for VNIR Precision: up to 9 decimal places	Precision may not run to 9 if there are trailing zeroes.
minCollectedRowG SD	Minimum original collected GSD of the product in the row direction.	Range: 0.100-100.000 Precision: 3 decimal places	The Pan GSD is used for
maxCollectedRow GSD	Maximum original collected GSD of the product in the row direction.	Range: 0.100-100.000 Precision: 3 decimal places	Panchromatic and Pan- sharpened products; the MS GSD is used for MS products
meanCollectedRow GSD	Mean original collected GSD of the product in the row direction.	Range: 0.100-100.000 Precision: 3 decimal places	These value ranges are based on 0 to 45 degrees
minCollectedColGS D	Minimum original collected GSD of the product in the column direction.	Range: 0.100-100.000 Precision: 3 decimal places	with regard to VNIR.
maxCollectedColGS D	Maximum original collected GSD of the product in the column direction.	Range: 0.100-100.000 Precision: 3 decimal places	values will range from 0.1 to 100.000 which allows
meanCollectedCol GSD	Mean original collected GSD of the product in the column direction.	Range: 0.100-100.000 Precision: 3 decimal places	subsampling.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
meanCollectedGSD	Mean GSD of the original, collected row and column GSD.	Range: 0.100-100.000 Precision: 3 decimal places	
meanProductRowG SD	Mean GSD of the product in the row direction.	Range: 0.100-100.000 Precision: 3 decimal places	Applicable to Level 1B products only.
meanProductColGS D	Mean GSD of the product in the column direction.	Range: 0.100-100.000 Precision: 3 decimal places	Applicable to Level 1B products only.
meanProductGSD	Mean GSD of the product row and column GSD.	Range: 0.100-100.000 Precision: 3 decimal places	Applicable to Level 1B products only.
rowUncertainty	Mean position uncertainty in line and pixel directions. These are 3-sigma, one-dimensional values.	Precision: 2 decimal places	
colUncertainty	Mean position uncertainty in line and pixel directions These are 3-sigma, one-dimensional values.	Precision: 2 decimal places	
minSunAz	Minimum azimuth angle of the sun measured from north clockwise.	Range: 0.0 to 360.0 Precision: One decimal point	
maxSunAz	Maximum azimuth angle of the sun measured from north clockwise.	Range: 0.0 to 360.0 Precision: One decimal point	
meanSunAz	Mean azimuth angle of the sun measured from north clockwise.	Range: 0.0 to 360.0 Precision: One decimal point	
minSunEl	Minimum elevation angle of the sun from horizontal.	Range: ± 90.0 Precision: One decimal point	
maxSunEl	Maximum elevation angle of the sun from horizontal.	Range: ± 90.0 Precision: One decimal point	
meanSunEl	Mean elevation angle of the sun from horizontal.	Range: ± 90.0 Precision: One decimal point	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
minSatAz	Minimum azimuth angle of the satellite with respect to the center line, in degrees.	Range: 0.0 to 360.0 Precision: One decimal point	
maxSatAz	Maximum azimuth angle of the satellite with respect to the center line.	Range: 0.0 to 360.0 Precision: One decimal point	
meanSatAz	Mean azimuth angle of the satellite with respect to the center line.	Range: 0.0 to 360.0 Precision: One decimal point	
minSatEl	Minimum elevation angle of the satellite with respect to the center line.	Range: ± 90.0 Precision: One decimal point	
maxSatEl	Maximum elevation angle of the satellite with respect to the center line.	Range: ± 90.0 Precision: One decimal point	
meanSatEl	Mean elevation angle of the satellite with respect to the center line.	Range: ± 90.0 Precision: One decimal point	
minInTrackViewAn gle	Minimum dihedral angle measured at the spacecraft from the nominal spacecraft YZ plane to the plane that contains the ground projection of the product center-line and the spacecraft Y-axis. A positive angle indicates the sensor is looking forward.	Range: ± 90.0 Precision: One decimal point	
maxInTrackViewAn gle	Maximum dihedral angle measured at the spacecraft from the nominal spacecraft YZ plane to the plane that contains the ground projection of the product center-line and the spacecraft Y-axis. A positive angle indicates the sensor is looking forward.	Range: ± 90.0 Precision: One decimal point	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
meanInTrackViewA ngle	Mean dihedral angle measured at the spacecraft from the nominal spacecraft YZ plane to the plane that contains the ground projection of the product center-line and the spacecraft Y-axis. A positive angle indicates the sensor is looking forward.	Range: ± 90.0 Precision: One decimal point	
minCrossTrackVie wAngle	Minimum dihedral angle measured at the spacecraft from the nominal spacecraft XZ plane to the plane that contains the ground projection of the product center-line and the spacecraft X-axis. A positive angle indicates the sensor is looking to the right.	Range: ± 90.0 Precision: One decimal point	
maxCrossTrackVie wAngle	Maximum dihedral angle measured at the spacecraft from the nominal spacecraft XZ plane to the plane that contains the ground projection of the product center-line and the spacecraft X-axis. A positive angle indicates the sensor is looking to the right.	Range: ± 90.0 Precision: One decimal point	
meanCrossTrackVi ewAngle	Mean dihedral angle measured at the spacecraft from the nominal spacecraft XZ plane to the plane that contains the ground projection of the product center-line and the spacecraft X-axis. A positive angle indicates the sensor is looking to the right.	Range: ± 90.0 Precision: One decimal point	
minOffNadirViewA ngle	The minimum spacecraft elevation angle measured from nadir to the product center-line as seen from the spacecraft.	Range: 0.0 to 90.0 Precision: One decimal place	
maxOffNadirViewA ngle	The maximum spacecraft elevation angle measured from nadir to the product center-line as seen from the spacecraft.	Range: 0.0 to 90.0 Precision: One decimal place	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
meanOffNadirView Angle	The mean spacecraft elevation angle measured from nadir to the product center-line as seen from the spacecraft.	Range: 0.0 to 90.0 Precision: One decimal place	
PNIIRS	Mean predicted image quality on the National Imagery Interpretability Rating Scale (NIIRS), as computed by the General Image Quality Equation (GIQE).	0.0 to 9.0	
cloudCover	Estimate of the max cloud-covered fraction of the product component For mosaic products, this calculation is based on the intersection of the polygons contained in the MOSAIC_CLOSEDPOLYGONS shapefile with the cloud polygons associated with that part of the relevent input imagery.	0.000 to 1.000 -999.000	-999.000 if not assessed
resamplingKernel	Method used to resample the image. "NULL"=no resampling kernel "NN"=nearest neighbor "CC"=cubic convolution "MTF"=Modulation Transfer Function "PS"=Pan sharpening "ENH"=Enhanced (Boost) kernel "UserDefined"	"NULL" "NN" "CC" "MTF" "PS" "ENH" "UserDefined"	Only valid when doing radiometric correction.
positionKnowledge Src	Source of knowledge of the satellite position. "R" = Refined	"R"	
attitudeKnowledge Src	Source of knowledge of the satellite attitude. "R" = Refined	"R"	
revNumber	Orbit revolution number at the time of exposure.	Range: 1 to 99999	
BEGIN_GROUP=IMAGE_n			
Only for map-projected BEGIN_GROUP=MAP_PROJECTED_PRODUCT (LV2A, LV3 and DEM) and Stereo OR2A products.			Only for map-projected (LV2A, LV3 and DEM) and Stereo OR2A products.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
earliestAcqTime	Acquisition time (UTC) of the first line of the earliest image contained in the product component.	YYYY-MM- DDThh:mm:ss.ddddddZ	
latestAcqTime	Acquisition time (UTC) of the first line of the latest image contained in the product component.	YYYY-MM- DDThh:mm:ss.ddddddZ	For a single image product this value will be the same as earliestAcqTime.
datumName	Name of the datum specified for the map projection when the product was ordered.	Value: WGS84: "WE" GRS 80: "GRS80" NAD83: "NAR" NAD27: "NAS" Tokyo-Mean: "TOKYO Mean Solution"	NAD83 uses a GRS 80 ellipsoid. NAD27 uses a Clarke 1866 ellipsoid. Tokyo-Mean uses a Bessel 1841 ellipsoid. Validation should support a 2 to 40 character length.
semiMajorAxis	Length of semi-major axis of the datum ellipsoid, in meters.	Value: WGS84/NAD83/GRS80: 6378137.0000 NAD27: 6378206.4000 Tokyo-M: 6377397.1550 Precision: 4 decimal places	
inverseFlattening	Inverse flattening of the datum ellipsoid, 1/f. Some useful relationships between flattening (f), semi-major axis (a), semi-minor axis (b), and eccentricity squared (e2) are: f = (a - b) / a e2 = (a2 - b2) / a2 = 2f - f2 b = a (1 - f)	Value: WGS84: 298.257223563 NAD83: 298.257222101 NAD27: 294.978698200 Tokyo-M: 299.152812800 Precision: 9 decimal places	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
datumOffset	X, Y, Z offset of the center of the reference ellipsoid relative to the origin of the WGS 84 system.	Values: For WGS84 & NAD83: (0.000, 0.000, 0.000); For NAD27: (-8.000, 160.000, 176.000); For Tokyo-Mean: (-128.000, 481.000 664.000) Precision: 3 decimal places	
mapProjName	Name of the map projection specified when the product was ordered.	"UTM" "State Plane Coordinates" "Japan RCS Zone xx" "Geographic (Lat/Long)"	For Japan RCS Zone, valid zone number range from 1 to 19.
mapProjCode	Integer code for the map projection that was used.	Values: UTM: 1 State Plane Coordinates: 2 Geographic (Lat/Long): 17	
mapZone	Zone used for the map projection.	Values: UTM: 1 to 60 State Plane: 0101 – 5105	Only for UTM and State Plane projections. State Plane must have all four digits present. For validation purposes, this should be evaluated as a whole number from 1-4 digits.
mapHemi	Code indicating the hemisphere used for the map projection.	"N" "S"	Only for UTM projection
mapProjParam	A list of 15 parameters that describe the particular map projection. The meaning of each parameter depends on the map projection selected in mapProjCode.	Precision: 9 decimal places	


FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
productUnits	Units of projected product	Precision: "DD" = Decimal Degrees "M" = Meters "F" = Feet "USF" = US Survey Feet	
originX	Easting of the center of the upper left pixel of the image.	Precision: 8 decimal places	This is equal to ULX unless an origin is specified by the customer.
originY	Northing of the center of the upper left pixel of the image.	Precision: 8 decimal places	This is equal to ULY unless an origin is specified by the customer.
orientationAngle	Azimuth angle measured clockwise from map north to the "up" direction at the center of the image. This is a rotation between raster image and the map coordinate systems. Since map- projected products are always Map- North up, this is always zero.	0.0	
colSpacing	GSD of the image in the column direction.	Values: colSpacing: 2 decimal places for non-geographic projected products colSpacing: scientific notation for geographic projected products	Not applicable to DEMs.
rowSpacing	GSD of the image in the row direction.	Values: rowSpacing: 2 decimal places for non-geographic projected products rowSpacing: scientific notation for geographic projected products	Not applicable to DEMs.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
productGSD	GSD of the product.	Range: .1-100.00 Precision: 2 decimal places	Standard (level 2A) and higher products only. The GSD of a MultiSpectral image needs to equal 4x the GSD of the PAN image. For example, if the productGSD of a PAN image is 0.50, then the productGSD of the MultiSpectral image will be 2.00. For validation, this shall range from 0.10 to 99.9.
edgeMatch	Indication of the use of edge matching for ortho-mosaic products. In other words, bundle-adjusted.	"On" "Off"	Orthorectified (level 3) products only.
colorBalance	Indication of the use of color balance for ortho-mosaic products.	"On" "Off"	Orthorectified (level 3) products only.
postSpacing	Post spacing on the DEM, in m.	Precision: 2 decimal places	Only applicable to DEMs.
ULX	Easting of the upper left pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	This value will be equal to originX.
ULY	Northing of the upper left pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	This value will be equal to originY.
ULH	Height above the ellipsoid of the upper left pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 2 decimal places	
URX	Easting of the upper right pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	
URY	Northing of the upper right pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	



FIELD	FIELD NAME / DESCRIPTION	ELD NAME / FORMAT RANGE / ESCRIPTION VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	
URH	Height above the ellipsoid of the upper right pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 2 decimal places	
LRX	Easting of the lower right pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	
LRY	Northing of the lower right pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	
LRH	Height above the ellipsoid of the lower right pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 2 decimal places	
LLX	Easting of the lower left pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	
LLY	Northing of the lower left pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 8 decimal places	
LLH	Height above the ellipsoid of the lower left pixel of the image in the specified datum and map projection. Includes blackfill.	Precision: 2 decimal places	
horizontalAccuracy	Accuracy in location position on finished DEM product. (1.6 sigma, 90% circular error)	0.0 to 200.0	DEM Products only.
verticalAccuracy	Accuracy of elevation determination on finished DEM product. (1.6 sigma, 90% linear error)	0.0 to 200.0	DEM Products only.



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS	
DEMCorrection	Level of the DEM used for the terrain correction.	"none" "Base Elevation" "Coarse DEM" "Fine DEM" "Customer Supplied DEM" "DTED1" "DTED2" "DTED3" "DTED4" "DTED5" "DTED6"	Not applicable to DEMs. Stereo OR2A and Standard OR2A Products use only "Base Elevation". Standard (level 2A) and Orthorectified (level 3) Products use anything except "none". All other products use "none".	
terrainHAE	The constant value of the height above the ellipsoid that was used for the terrain correction, in meters.	Range: -50000 to 50000	Only when DEMCorrection = "Base Elevation".	
numGCP	Number of ground control points used to create this product.	Range: ≥ 0		
END_GROUP=MAP_PROJECTED_PRODUCT				
END;				

6.1.1 Heights Above Ellipsoid (HAE)

The heights above the ellipsoid listed in the band section of the Image Metadata Data (IMD) may vary from the heights above the ellipsoid listed in the map projection section depending on the datum and the DEM correction used. For example:

- Case 1: DEM = Base Elevation; and datum = WGS-84 In this case the band and the map heights will all be the same, equivalent to the value of terrainHAE.
- Case 2: DEM = Base Elevation; but datum ≠ WGS-84 (that is, Tokyo Mean)
 In this case the map heights will all be the same, and equivalent to the value listed in terrainHAE. However, the heights
 listed in the band section may not equal this value (although they may appear to be equal, but differ in decimal places
 not shown due to the decimal precision). This difference is due to a conversion using the WGS84 ellipsoid, which
 changes the height values slightly.
- Case 3: DEM = Coarse/Fine DEM; and datum = WGS-84 In this case, the heights listed in the map section will vary, as will the heights in the band section. However, the corresponding heights will be equal. For example, ULHAE will be the same as ULH.
- Case 4: DEM = Coarse/Fine DEM; but datum ≠ WGS-84 (that is, Tokyo Mean) All heights listed are likely to vary for the same reason listed in Case 2.



6.1.2 Product Level to Product Type Relationships

Table 6.2	Product	level to	Product	Type	Relationshi	ns
	FIOUULL	Leveito	FIUUULL	Type	Relationsin	ps

PRODUCT LEVEL	PRODUCT TYPE	MAP ACCURACY
LV1B	Basic	N/A
LV2A	Standard	N/A
LV3A	Orthorectified	1:50,000
LV3D	Orthorectified	1:12,000
LV3E	Orthorectified	1:10,000
LV3F	Orthorectified	1:5,000
LV3G	Orthorectified	1:4,800
LV3X	Orthorectified	Custom
Stereo 1B	Basic Stereo pair	N/A
Stereo OR2A	Ortho-ready Standard	N/A
LV4	Various: DEM or Value-Added	Various

6.2 Product Browse File

The product browse file is a compressed JPEG file of the delivered product. The product browse file will be consistent with the bands ordered for the final product, except for multispectral and 4-band pan-sharpened products for which natural color browse imagery will be supplied. Figure 6.1 is sample of a natural color-product browse file.



Figure 6.1 Sample Product Browse File



6.3 Tile Map

Large images are tiled into sub-images and distributed as a group of sub-image files, called tiles. Tiles are not uniform in size. If the image does not fill the whole tile, blackfill will be added to the top and left of the imagery, but removed from the bottom and right of the imagery in order to maintain a uniform upper left pixel and reduce tile sizes. Blackfill will only be present in the upper left corner of a product if a tiling origin is specified that does not correspond to the upper left corner of the Order polygon. If no tiling origin is specified, the upper left corner of the order poly will be the tiling origin by default. This section describes the PVL-format tile map file and part of the XML file. It provides the row and column offset for the upper left corner of each tile, relative to the upper left corner of the base image product. For map-projected image products (Standard and Orthorectified), it also provides the latitude and longitude of the upper left pixel in the tile. Table 6.3 defines the Tile Map contents.

Table 6.3 Tile Map Contents

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
bandld	Identifies the spectral band. "P" = Panchromatic, "Multi" = all Multi-spectral bands (4 for QB02, GE01 and 8 for WV02, WV03) "N" = Near–InfraRed "R" = Red, "G" = Green "B" = Blue "RGB" = Red + Green + Blue "RGB" = Near-IR + Red + Green "BGRN" = Blue + Green + Red + Near-IR RGB, NRG, and BGRN are pan-sharpened color images, stored at the panchromatic spatial resolution. For WorldView-2 and WorldView-3 there are also the following bands: "N2"=NIR2 "RE"=Red Edge "Y"=Yellow "C"=Coastal "MS1"=First 4 bands (N,R,G,B) "MS2"=Second 4 bands (N2,RE,Y,C) For a DEM, this field indicates the spectral band used to create the product.	"P" "Multi" "N" "R" "G" "B" "RGB" "NRG" "BGRN" "NG" "BGRN" "N2" "RE" "Y" "C" "MS1" "MS2"	N2, RE, Y and C in any band combination are available for WorldView-2 and WorldView-3 only. For validation, this field is constrained by the following definition: A-Za-z0-9 (alphanumeric) plus '-' for up to 7 (1 to 7) characters
numTiles	The number of tiles for this product.	Range: ≥ 1	
tileSizeX	Size of the X component (columns) of each tile.	Range: ≥ 1	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
tileSizeY	Size of the Y component (lines) of each tile.	Range: ≥ 1	
tileUnits	Units of tiles	"Pixels" "Meters" "Feet" "Degrees"	Degrees only applicable for DOQQ products.
tileOverlap	Overlap of tiles.	Range: ≥ 0	
	The following group is repeated for $n = 1$,,numTiles. That is, once for each of t	the tiles.
	BEGIN_C	GROUP=TILE_n	
filename	Filename of the tile.	Example: "10JUL04165542-P2AS- 052380211010_01_P001.NTF"	
ULColOffset	Column offset of the upper left pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: (columnNum-1)*tileSizeX The columnNum can be found in the filename. For example, "2" in R1C2.]	Range: 0 to ((maxCol-1)*tileSizeX)	
ULRowOffset	Row offset of the upper left pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: (rowNum-1) * tileSizeY The rowNum can be found in the filename. For example, "1" in R1C2.]	Range: 0 to ((maxRows-1)*tileSizeY)	
URColOffset	Column offset of the upper right pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: MIN((columnNum*tileSizeX), maximumProductTtileSizeX)-1 The columnNum can be found in the filename. For example, "2" in R1C2.]	Range: – (tileSizeX-1) to (maximumProductTileSizeX-1)	
URRowOffset	Row offset of the upper right pixel of this tile, relative to the upper left pixel of the base image.	Range: 0 to ((maxRows-1)*tileSizeY)	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
	[This field is calculated as: (rowNum-1)*tileSizeY The rowNum can be found in the filename. For example, "1" in R1C2.]		
LRColOffset	Column offset of the lower right pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: MIN((columnNum*tileSizeX), maximumProductTtileSizeX)-1 The columnNum can be found in the filename. For example, "2" in R1C2.]	Range: – (tileSizeX-1) to (maximumProductTileSizeX-1)	
LRRowOffset	Row offset of the lower right pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: MIN((rowNum*tileSizeY), maximumProductTtileSizeY)-1 The rowNum can be found in the filename. For example, "1" in R1C2.]	Range: – (tileSizeY-1) to (maximumProductTileSizeY-1)	
LLColOffset	Column offset of the lower left pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: (columnNum -1)*tileSizeX The columnNum can be found in the filename. For example, "2" in R1C2.]	Range: 0 to ((maxCol-1)*tileSizeX)	
LLRowOffset	Row offset of the lower left pixel of this tile, relative to the upper left pixel of the base image. [This field is calculated as: MIN(rowNum*tileSizeY), maximumProductTtileSizeY)-1 The rowNum can be found in the filename. For example, "1" in R1C2.]	Range: – (tileSizeY-1) to (maximumProductTileSizeY-1)	
ULLon	The geodetic longitude of the center of the upper left pixel in the tile.	Range: ± 180.00000000 Precision: 8 decimal places	
ULLat	The geodetic latitude of the center of the upper left pixel in the tile.	Range: ± 90.00000000 Precision: 8 decimal places	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
URLon	The geodetic longitude of the center of the upper right pixel in the tile.	Range: ± 180.00000000 Precision: 8 decimal places	
URLat	The geodetic latitude of the center of the upper right pixel in the tile.	Range: ± 90.00000000 Precision: 8 decimal places	
LRLon	The geodetic longitude of the center of the lower right pixel in the tile.	Range: ± 180.00000000 Precision: 8 decimal places	
LRLat	The geodetic latitude of the center of the lower right pixel in the tile.	Range: ± 90.00000000 Precision: 8 decimal places	
LLLon	The geodetic longitude of the center of the lower left pixel in the tile.	Range: ± 180.00000000 Precision: 8 decimal places	
LLLat	The geodetic latitude of the center of the lower left pixel in the tile, in degrees.	Range: ± 90.00000000 Precision: 8 decimal places	
ULX	Easting of the center of the upper left pixel of the tile in the specified map projection, datum, and units of the product.	Value: Precision: 8 decimal places	
ULY	Northing of the center of the upper left pixel of the tile in the specified map projection, datum, and units of the product.	Precision: 8 decimal places	
URX	Easting of the center of the upper right pixel of the tile in the specified map projection, datum, and units of the product.	Precision: 8 decimal places	
URY	Northing of the center of the upper right pixel of the tile in the specified map projection, datum, and units of the product.	Precision: 8 decimal places	
LRX	Easting of the center of the lower right pixel of the tile in the specified map projection, datum, and units of the product.	Precision: 8 decimal places	
LRY	Northing of the center of the lower right pixel of the tile in the specified map	Precision: 8 decimal places	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
	projection, datum, and units of the product.		
LLX	Easting of the center of the lower left pixel of the tile in the specified map projection, datum, and units of the product.	Precision: 8 decimal places	
LLY	Northing of the center of the lower left pixel of the tile in the specified map projection, datum, and units of the product.	Precision: 8 decimal places	
	END_G	ROUP=TILE_n	
		END;	

6.4 Rational Polynomial Coefficients

This section describes the content of the PVL-format RPC00B file and the corresponding part of the XML file. It contains the coefficients for Rapid Positioning Capability, also called Rational Polynomial Coefficients (RPC). This is a mathematical mapping from object space coordinates to image space coordinates. This mapping includes non-ideal imaging effects, such as lens distortion, light aberration, and atmospheric refraction.

RPC00Bs express the normalized column and row values in an image, (c_n, r_n) , as a ratio of polynomials of the normalized geodetic latitude, longitude, and height, (P, L, H). Normalized values are used instead of actual values in order to minimize numerical errors in the calculation. The scales and offset of each parameter are selected so that all normalized values fall in the range [-1, 1]. The normalization used is as follows:

- P = (Latitude LAT_OFF) / LAT_SCALE
- L = (Longitude LONG_OFF) / LONG_SCALE
- H = (Height HEIGHT_OFF) / HEIGHT_SCALE
- r_n = (ROW LINE_OFF) / LINE_SCALE
- c_n = (Column SAMP_OFF) / SAMP_SCALE

Each polynomial is up to third order in (P, L, H), having as many as 20 terms. The rational functions are:

$$r_{n} = \frac{\sum_{i=1}^{20} LINE _NUM _COEF_{i} \bullet p_{i}(P, L, H)}{\sum_{i=1}^{20} LINE _DEN _COEF_{i} \bullet p_{i}(P, L, H)} \quad and \quad c_{n} = \frac{\sum_{i=1}^{20} SAMP _NUM _COEF_{i} \bullet p_{i}(P, L, H)}{\sum_{i=1}^{20} SAMP _DEN _COEF_{i} \bullet p_{i}(P, L, H)}$$

LINE_NUM_COEF, LINE_DEN_COEF, SAMP_NUM_COEF, and SAMP_DEN_COEF are 20-term vectors of coefficients that are given in the RPC00B file. *p*(*P*,*L*,*H*) is a 20-term vector with the following terms:



I	p _i (P,L,H)	I	p _i (P,L,H)
1	1	11	PLH
2	L	12	L ³
3	Р	13	LP ²
4	Н	14	LH ²
5	LP	15	L ² P
6	LH	16	P ³
7	РН	17	PH ²
8	L ²	18	L ² H
9	P ²	19	P ² H
10	H ²	20	H ³

Table 6.4 RPC Terms

For example, for a generic set of polynomial coefficients Ci, the corresponding 20-term cubic polynomial has the form:

 $f(P, L, H) = C_1 + C_2 L + C_3 P + C_4 H + C_5 LP + C_6 LH + C_7 PH + C_8 L^2 + C_9 P^2 + C_{10} H^2 + C_{11} PLH + C_{12} L^3 + C_{13} LP^2 + C_{14} LH^2 + C_{15} L^2 P + C_{16} P^3 + C_{17} PH^2 + C_{18} L^2 H + C_{19} P^2 H + C_{20} H^3$

The image coordinates are expressed in pixels. The ground coordinates are latitude and longitude in decimal degrees, and geodetic elevations (height above the ellipsoid) in meters.

There is only one set of coefficients for Basic, Stereo, and Standard products since their multi-spectral bands are coregistered and the images are geometrically continuous within each band. The range of values for each numeric parameter is as specified in The Compendium of Controlled Extensions (CE) for the National Imagery Transmission Format (NITF); NIMA document STDI-0002, Version 2.1, 16 November 2000. Out-of-range coefficients are set to zero. Table 6.5 defines the RPC00B contents.

Table 6.5 RPC00B Contents

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
satId	Satellite Id.	"QB02", "WV01", "WV02", "GE01", "WV03"	
bandld	Identifies the spectral band. "P" = Panchromatic,	"P" "Multi" "N"	N2, RE, Y and C in any band combination are available for



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
	 "Multi" = all Multi-spectral bands (4 for QB02, GE01 and 8 for WV02, WV03), "N" = Near-InfraRed, "R" = Red, "G" = Green, "B" = Blue, "RGB" = Red + Green + Blue, "NRG" = Near-IR + Red + Green, "BGRN" = Blue + Green + Red + Near- IR. RGB, NRG, and BGRN are pan- sharpened color images, stored at the panchromatic spatial resolution. For WorldView-2 and WorldView-3 there are also the following bands, "N2"=NIR2, "RE"=Red Edge, "Y"=Yellow, "C"=Coastal "MS1" "MS2" For a DEM, this field indicates the spectral band used to create the product. 	"R" "G" "RGB" "NRG" "BGRN" "N2" "RE" "Y" "C" "MS1" "MS2"	WorldView-2 and WorldView-3 only.
SpecId	Identification of the specification which defines the RPC implementation used for generating and/or interpreting the coefficients	"RPC00B"	
	BEGIN_GROUP = IMAGI	E	Standard (level 2A) and Orthorectified (level 3) products only.
errBias	Bias error. 68% non time-varying error estimate for correlated images.	Range: 0.00 – 9999.99 Precision: 2 decimal places	
errRand	Random error. 68% time-varying error estimate for correlated images.	Range: 0.00 – 9999.99 Precision: 2 decimal places	
lineOffset	LINE_OFFSET.	Range: 0 – 999999	
sampOffset	SAMP_OFFSET.	Range: -9999 to 99999	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
latOffset	LAT_OFFSET.	Range: ± 90.0000 Precision: 4 decimal places	
longOffset	LONG_OFFSET.	Range: ± 180.0000 Precision: 4 decimal places	
heightOffset	HEIGHT_OFFSET.	Range: ± 9999	
lineScale	LINE_SCALE	Range: 1 – 999999	
sampScale	SAMP_SCALE	Range: 1 – 99999	
latScale	LAT_SCALE	Range: ± 90.0000 Precision: 4 decimal places	
longScale	LONG_SCALE	Range: ± 180.0000 Precision: 4 decimal places	
heightScale	HEIGHT_SCALE	Range: ± 9999	
lineNumCoef	LINE_NUM_COEF. Twenty coefficients for the polynomial in the numerator of the r_n equation.	Range: \pm 9.999999 * 10 ^{\pm 9}	
lineDenCoef	LINE_DEN_COEF. Twenty coefficients for the polynomial in the denominator of the r_n equation.	Range: \pm 9.999999 * 10 ^{\pm 9}	
sampNumCoef	SAMP_NUM_COEF. Twenty coefficients for the polynomial in the numerator of the c_n equation.	Range: \pm 9.999999 * 10 ^{\pm 9}	
sampDenCoef	SAMP_DEN_COEF. Twenty coefficients for the polynomial in the denominator of the c_n equation.	Range: \pm 9.999999 * 10 ^{\pm 9}	
END;			

6.5 Product Component XML File

The XML file contains the same information as the combined product component level README, Licensing, Image Metadata, Tile Map, and RPC00B files, except in XML format. For Basic Imagery Products, the attitude, ephemeris, and geometric calibration file are included as well. One Product Component XML file is provided for each product component of each delivery within the product component subdirectory.

Listed below is an example of this file for a Bundle Standard Imagery Product.



<?xml version="1.0" encoding="UTF-8" ?>

- <README>

<VERSION>AA</VERSION>

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<CUSTOMERORDERNO>PS_02 1B+ BA XML Taipei</CUSTOMERORDERNO>
<CUSTOMERORDERITEMNO>40009</CUSTOMERORDERITEMNO>
<COLLECTIONSTART>2002-12-15T02:38:08.618201Z</COLLECTIONSTAR>
<COLLECTIONSTOP>2003-08-09T02:18:48.385340Z</COLLECTIONSTOP>
<COUNTRYCODE>TW</COUNTRYCODE>
<NUMBEROFLOOKS>1</NUMBEROFLOOKS>
<CLOUDCOVER>-999.0</CLOUDCOVER>
<NWLAT>25.12000000</NWLAT>
<NWLONG>121.6000000</NWLONG>
<SELAT>25.0400000</SELAT>
<SELONG>121.73000000</SELONG>
</README>
```

6.6 Manifest File

The manifest file outlines the directory structure for products delivered by FTP. Below is an example of the manifest file delivered for a Standard Pansharpened Imagery product.

```
./005510916010_01.MAN
./005510916010_01
./005510916010_01/005510916010_01_README.TXT
./005510916010_01/005510916010_01_README.XML
./005510916010_01/005510916010_01_LAYOUT.JPG
./005510916010_01/GIS_FILES
./005510916010_01/GIS_FILES/005510916010_01_ORDER_SHAPE.shx
./005510916010_01/GIS_FILES/005510916010_01_ORDER_SHAPE.shp
./005510916010_01/GIS_FILES/005510916010_01_ORDER_SHAPE.dbf
./005510916010_01/GIS_FILES/005510916010_01_PRODUCT_SHAPE.shx
./005510916010_01/GIS_FILES/005510916010_01_PRODUCT_SHAPE.shp
./005510916010_01/GIS_FILES/005510916010_01_PRODUCT_SHAPE.dbf
./005510916010_01/GIS_FILES/005510916010_01_STRIP_SHAPE.shx
./005510916010_01/GIS_FILES/005510916010_01_STRIP_SHAPE.shp
./005510916010_01/GIS_FILES/005510916010_01_STRIP_SHAPE.dbf
./005510916010_01/GIS_FILES/005510916010_01_TILE_SHAPE.shx
./005510916010_01/GIS_FILES/005510916010_01_TILE_SHAPE.shp
./005510916010_01/GIS_FILES/005510916010_01_TILE_SHAPE.dbf
./005510916010_01/005510916010_01_P001_PSH
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS-
005510916010_01_P001_README.TXT
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS-005510916010_01_P001.IMD
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS-005510916010_01_P001.TIL
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS-005510916010_01_P001.RPB
./005510916010_01/005510916010_01_P001_PSH/COMMERCIAL.TXT
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS-005510916010_01_P001.XML
```



./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS-005510916010_01_P001-BROWSE.JPG ./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R1C1-005510916010_01_P001.TIF

```
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R1C2-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R1C3-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R2C1-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C2-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C2-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R4C1-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R4C2-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R4C2-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C3-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C3-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C3-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C3-005510916010_01_P001.TIF
./005510916010_01/005510916010_01_P001_PSH/03MAR13174755-S2AS_R3C3-005510916010_01_P001.TIF
```

6.7 Stereo File

This file is provided only for Stereo Pair Imagery products, and describes information about individual stereo models. The stereo file contains three angular measures of convergent stereo imaging geometry: the convergence angle, the asymmetry angle, and the bisector elevation angle (BIE). These measure the geometrical relationship between two rays that intersect at a common ground point, one from the fore image and one from the aft image. These intersecting rays define a plane, called the convergence plane. The convergence angle is the angle between the two rays in the convergence plane. The asymmetry angle is the angle between the ray bisector (also in the convergence plane), and the projection of a vertical from the ground point onto the convergence plane. The BIE is the elevation of the bisector. That is, the angle from the horizontal plane containing the ground point to the bisector. Each angle is computed at a ground target point near the beginning of the stereo overlap, and at another point near the end of the stereo overlap. Table 6.6 defines the Stereo File contents.



Figure 6.2 Stereo Geometry Angles

Stereo geometry is often described in terms of convergence angle and asymmetry angle at a ground point defined by radius vector, as illustrated in Figure 6.2. These angles are measured in the plane formed by the two lines of sight (one for each image) to the ground point.



Table 6.6 Stereo File Contents

FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
numPair	Number of stereo pairs in this file.	1	
	The following group is repeated for n =	1,,numPair (for all stereo pairs).	
	BEGIN_GROUP=ST	EREO_PAIR_n	
firstld	Image file name of the first image (image acquired at the earlier time) of a stereo pair.	For products produced by DigitalGlobe, this name will follow the standard product naming conventions.	
secondId	Image file name of the second image of the stereo pair.	See firstID.	
overlap	Fractional overlap: overlap area, measured on the ground, divided by the ground area of the second image.	0.00 to 1.00	
ULLat	Geodetic latitude of the upper left corner of the minimum-bounding rectangle that covers the stereo model.	Range: ± 90.000000 Precision: Six decimal places	
ULLon	Geodetic longitude of the upper left corner of the minimum-bounding rectangle that covers the stereo model.	Range: ± 180.000000 Precision: Six decimal places	
LRLat	Geodetic latitude of the lower right corner of the minimum-bounding rectangle that covers the stereo model.	Range: ± 90.000000 Precision: Six decimal places	
LRLon	Geodetic longitude of the lower right corner of the minimum-bounding rectangle that covers the stereo model.	Range: ± 180.000000 Precision: Six decimal places	
B_Conv	Beginning convergence angle. This is measured at the first lines of the stereo overlap.	Range: 0.00 to 180.00 Precision: Two decimal places	
E_Conv	Ending convergence angle. This is measured at the last lines of the stereo overlap.	Range: 0.00 to 180.00 Precision: Two decimal places	
B_Asym	Beginning asymmetry angle. This is measured at the first lines of the stereo overlap.	Range: 0.00 to 90.00 Precision: Two decimal places	



FIELD	FIELD NAME / DESCRIPTION	FORMAT RANGE / VALUE [DG RANGE / VALUE, IF DIFFERENT FROM FORMAT RANGE / VALUE]	CONDITIONS / COMMENTS
E_Asym	Ending asymmetry angle. This is measured at the last lines of the stereo overlap.	Range: 0.00 to 90.00 Precision: Two decimal places	
B_BIE	Beginning BIE less convergence angle of stereo mate. This is measured at the first lines of the stereo overlap.	Range: -90.00 to 90.00 Precision: Two decimal places	
E_BIE	Ending BIE less convergence angle of stereo mate. This is measured at the last lines of the stereo overlap.	Range: -90.00 to 90.00 Precision: Two decimal places	
END_GROUP=STEREO_PAIR_n			
END;			



Appendix A: Example PVL Format

The following is an example PVL format. It is for illustration purposes only.

```
/* ISD Version */
        version = "21.0";
generationTime = 2003-12-18T17:54:28.000000Z;
productOrderId = "T-111-C";
productCatalogId = "2030011234567801";
imageDescriptor = "Standard2A";
bandId = "P";
panSharpenAlgorithm = "None";
numRows = 22472i
numColumns = 14384;
productLevel = "LV2A";
productType = "Standard";
numberOfLooks = 1;
radiometricLevel = "Corrected";
radiometricEnhancement = "Off";
bitsPerPixel = 8;
compressionType = "None";
BEGIN_GROUP = BAND_P
        ULLon = -158.26477950;
        ULLat = 21.59936003;
        ULHAE =
                    0.00;
        URLon = -158.13533250;
        URLat = 21.59936003;
        URHAE =
                    0.00;
        LRLon = -158.13533250;
        LRLat = 21.39712529;
        LRHAE =
                    0.00;
        LLLon = -158.26477950;
        LLLat = 21.39712527;
LLHAE = 0.00;
        absCalFactor = 4.734886e-01;
        effectiveBandwidth = 3.9800e-01;
END_GROUP = BAND_P
outputFormat = "GeoTIFF";
BEGIN_GROUP = IMAGE_1
        satId = "QB02";
        mode = "FullSwath";
        CatId = "101001000173E700";
        minCollectedRowGSD = 0.618;
maxCollectedRowGSD = 0.621;
        meanCollectedRowGSD = 0.619;
        minCollectedColGSD = 0.629;
        maxCollectedColGSD = 0.630;
meanCollectedColGSD = 0.629
                                0.629;
        meanCollectedGSD = 0.624;
        rowUncertainty = 166.70;
colUncertainty = 292.81;
        minSunAz = 155.3;
        maxSunAz = 156.8;
        meanSunAz = 155.8;
        minSunEl = 43.2;
        maxSunEl = 44.2;
        meanSunEl = 43.7;
        minSatAz = 119.7;
        maxSatAz = 119.9;
        meanSatAz = 119.8;
        minSatEl = 80.0;
        maxSatEl = 82.0;
        meanSatEl = 81.1;
        minInTrackViewAngle = -3.4;
```



```
maxInTrackViewAngle = -1.4;
       meanInTrackViewAngle = -2.4;
       minCrossTrackViewAngle = 8.6;
       maxCrossTrackViewAngle = 15.6;
       meanCrossTrackViewAngle = 11.8;
       minOffNadirViewAngle = 9.2;
       maxOffNadirViewAngle = 17.2;
       meanOffNadirViewAngle = 12.2;
       PNIIRS = 3.8;
       cloudCover = 0.000;
       imageQuality = "Fair";
       TDILevel = 13;
       positionKnowledgeSrc = "R";
       attitudeKnowledgeSrc = "R";
       revNumber = 6279;
END_GROUP = IMAGE_1
BEGIN_GROUP = MAP_PROJECTED_PRODUCT
       earliestAcqTime = 2002-11-30T21:06:27.161677Z;
       latestAcqTime = 2002-11-30T21:06:27.161677Z;
       datumName = "INTERNATIONAL 1924";
       semiMajorAxis = 6378388.0000;
       inverseFlattening = 297.00000000;
       datumOffset = (
            0.000,
            0.000,
            0.000);
       mapProjName = "Geographic (Lat/Long)";
       mapProjCode = 17;
       mapProjParam = (
       6366197.723675813,
         0.00000000,
         0.00000000,
         0.00000000,
         0.00000000,
         0.00000000,
         0.00000000,
         0.00000000,
         0.00000000,
         0.00000000,
         0.000000000.
         0.00000000,
         0.000000000.
         0.00000000,
         0.00000000);
       productUnits = "DD";
       originX =
                     -158.26477950;
                        21.59992350;
       originY =
       orientationAngle =
                             0.0;
       colSpacing = 0.00;
       rowSpacing = 0.00;
        productGSD = 0.60;
       edgeMatch = "Off";
       colorBalance = "On";
       ULX =
              -158.26477950;
                21.59992350;
       ULY =
       ULH =
                  0.00;
       URX =
               -158.13533250;
                21.59992350;
       URY =
       URH =
                  0.00;
       LRX =
               -158.13533250;
                21.39768450;
       LRY =
       LRH =
                   0.00;
       LLX =
               -158.26477950;
       LLY =
                21.39768450;
       LLH =
                  0.00;
```



DEMCorrection = "none"; numGCP = 4; END_GROUP = MAP_PROJECTED_PRODUCT END; /* END OF MODULE */



Appendix B: Example XML Format

```
The following is an example XML format. It is for illustration purposes only.
<?xml version="1.0" encoding="UTF-8" ?>
<version>"21.0"</version>
<generationTime>2003-12-18T17:54:28.000000Z</generationTime>
<productOrderId>"T-111-C"</productOrderId>
cproductCatalogId> = "2030011234567801" </productCatalogId>
<imageDescriptor>"Standard2A"</imageDescriptor>
<bandId>"P"</bandId>
<panSharpenAlgorithm>"None"</panSharpenAlgorithm>
<numRows>22472 </numRows>
<numColumns>14384</numColumns>
<productLevel>"LV2A" </productLevel>
<productType>"Standard" </productType>
<numberOfLooks>1 </numberOfLooks>
<radiometricLevel>"Corrected"</radiometricLevel>
<radiometricEnhancement>"Off"</radiometricEnhancement>
<bitsPerPixel>8</bitsPerPixel>
<compressionType>"None"</compressionType>
<Band_P>
   <ULLon>-158.26477950</ULLon>
   <ULLat> 21.59936003</ULLat>
   <ULHAE> 0.00</ULHAE>
   <URLon> -158.13533250</URLon>
   <URLat> 21.59936003</URLat>
   <URHAE> 0.00</URHAE>
   <LRLon> -158.13533250</LRLon>
   <LRLat> 21.39712529</LRLat>
   <LRHAE> 0.00</LRHAE>
   <LLLon> -158.26477950</LLLon>
   <LLLat> 21.39712527</LLLat>
   <LLHAE> 0.00</LLHAE>
   <absCalFactor> 4.734886e-01</absCalFactor>
   <effectiveBandwidth> 3.9800e-01 <effectiveBandwidth>
</Band P>
<outputFormat>"GeoTIFF"</outputFormat>
<Image_List>
   <satId>"QB02"</satId>
   <mode>"FullSwath"</mode>
   <catId>"101001000173E700"</catId>
       <minCollectedRowGSD>0.618</minCollectedRowGSD>
       <maxCollectedRowGSD>0.621</maxCollectedRowGSD>
       <meanCollectedRowGSD>0.619</meanCollectedRowGSD>
       <minCollectedColGSD>0.629</minCollectedColGSD>
       <maxCollectedColGSD>0.630</maxCollectedColGSD>
       <meanCollectedColGSD>0.629</meanCollectedColGSD>
       <meanCollectedGSD>0.624</meanCollectedGSD>
       <rowUncertainty>166.70</rowUncertainty>
       <colUncertainty>292.81</colUncertainty>
       <minSunAz>155.3</minSunAz>
       <maxSunAz>156.8</maxSunAz>
       <meanSunAz>155.8</meanSunAz>
       <minSunEl>43.2</minSunEl>
       <maxSunEl>44.2</maxSunEl>
       <meanSunEl>43.7</meanSunEl>
       <minSatAz>119.7</minSatAz>
       <maxSatAz>119.9<maxSatAz>
       <meanSatAz>119.8<meanSatAz>
       <minSatEl>80.0</minSatEl>
       <maxSatEl>82.0</maxSatEl>
```



```
<meanSatEl>81.1</maxSatEl>
      <minInTrackViewAngle>-3.4</minInTrackViewAngle>
      <maxInTrackViewAngle>-1.4</maxInTrackViewAngle>
      <meanInTrackViewAngle>-2.4</meanInTrackViewAngle>
      <minCrossTrackViewAngle>8.6</minCrossTrackViewAngle>
      <maxCrossTrackViewAngle>15.6<maxCrossTrackViewAngle>
      <meanCrossTrackViewAngle>11.8<meanCrossTrackViewAngle>
      <minOffNadirViewAngle>9.2</minOffNadirViewAngle>
      <maxOffNadirViewAngle>17.2</maxOffNadirViewAngle>
      <meanOffNadirViewAngle>12.2<meanOffNadirViewAngle>
      <PNIIRS>3.8</pniiRS>
   <cloudCover>0.000</cloudCover>
   <imageQuality>"Fair"</imageQuality>
  <TDILevel>13</TDILevel>
   <positionKnowledgeSrc>R</positionKnowledgeSrc>
   <attitudeKnowledgeSrc>R</attitudeKnowledgeSrc>
   <revNumber>6279</revNumber>
</Image List>
<mapProjected>
                <earliestAcqTime>2002-11-30T21:06:27.161677Z</earliestAcqTime>
                <latestAcqTime>2002-11-30T21:06:27.161677Z</latestAcqTime>
                <datumName>"INTERNATIONAL 1924"</datumName>
                <semiMajorAxis>6378388.0000</semiMajorAxis>
                <inverseFlattening>297.00000000</inverseFlattening>
                <datumOffset>
                     <offset>0.000</offset>
                     <offset>0.000</offset>
                     <offset>0.000</offset>
                </datumOffset>
                <mapProjName>"Geographic (Lat/Long)" </mapProjName>
                <mapProjCode>17</mapProjCode>
                <mapProjParam>
                    <param> 6366197.723675813</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                    <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                     <param> 0.00000000</param>
                    <param> 0.00000000</param>
                </mapProjParam>
                oductUnits>"DD"</productUnits>
                <originX>-158.26477950</originX>
                <originY>21.59992350</originY>
                <orientationAngle>0.0</orientationAngle>
                <colSpacing>0.00</colSpacing>
                <rowSpacing>0.00</rowSpacing>
                   <productGSD>0.60</productGSD>
                <edgeMatch>"Off"</edgeMatch>
                <colorBalance>"On"</colorBalance>
                <ULX> -158.26477950</ULX>
                <ULY> 21.59992350</ULY>
                <ULH> 0.00</ULH>
                <URX> -158.13533250</URX>
                <URY> 21.59992350</URY>
                <URH> 0.00</URH>
                <LRX>-158.13533250</LRX>
                <LRY>21.39768450</LRY>
```



<LRH>0.00</LRH> <LLX>-158.26477950</LLX> <LLY>21.39768450</LLY> <LLH> 0.00</LLH> <DEMCorrection>"none"</DEMCorrection> <numGCP>4</numGCP>

</mapProjected>



Appendix C: Example Tile Map File

The following is an example tile map format. It is for illustration purposes only. bandId = "RGB"; numTiles = 12; tileSizeX = 8192; tileSizeY = 8192; tileUnits = "Pixels"; tileOverlap = 0; BEGIN_GROUP = TILE_1 filename = "02DEC15023809-S2AS_R1C1-005500420010_01_P001.NTF"; ULColOffset = 0; ULRowOffset = 0; URColOffset = 8191; URRowOffset = 0; LRColOffset = 8191; LRRowOffset = 8191; LLColOffset = 0; LLRowOffset = 8191; ULLon = 121.50000270; ULLat = 25.24998690; URLon = 121.54423410; URLat = 25.2499000 121.54423410; 20575550; 25.24998690; LRLon = 25.20575550; LRLat = LLLon = 121.50000270; LLLat = 25.20575550; ULX = 121.50000270; ULY = 25.24998690; URX = 121.54423410; URY = 25.24998690; LRX = 121.54423410; LRY = 25.20575550; LLX = 121.50000270; LLY = 25.20575550;



Glossary

AOI

Area of Interest. The area on the Earth that you want to view.

Bilinear Interpolation

Bilinear interpolation uses the value of the four nearest cell centers to determine the value on the output raster. The new value is a weighted average of these four values, adjusted to account for their distance from the center of the output cell. The result is a smoother-looking surface than provided by "nearest neighbor".

Bicubic Interpolation

Bicubic interpolation combines data points on a two-dimensional grid. This method outputs the smoothest surface of all interpolation methods.

CE

Circular Error.

CE90

Circular Error at 90% confidence. Indicates that the actual location of an object is represented on the image within the stated accuracy for 90% of the points.

CIR

Color Infrared.

COTS

Commercial-Off-The-Shelf.

DEM

See Digital Elevation Model.

Digital Elevation Model (DEM)

A digital model of terrain relief, usually derived from stereo imagery. A DEM is used to remove terrain distortions from Orthorectified Imagery products.

DRA

Dynamic Range Adjustment. An optional post-processing feature that enhances the visual interpretability of the image.

DTED

Digital Terrain Elevation Data.

ECF

Earth Centered Fixed.

FTP

File Transfer Protocol.

GCP

See Ground Control Point.



GE01

GeoEye-1 Satellite.

Geographic Projection

Maps longitudes as straight vertical lines and latitudes as straight horizontal lines all spaced out consistently for constant intervals.

GeoTIFF format

Georeferenced tagged image file format. A GeoTIFF file is a TIFF file that is embedded with geographic data tags.

Ground Control Point (GCP)

A known geographic coordinate location on the ground. A GCP can be collected from ground survey or maps (Primary GCP), or derived via triangulation of primary GCPs (Secondary GCP). GCPs can be planimetric (x, y; latitude, longitude) or vertical (x, y, z; latitude, longitude, elevation).

Ground Sample Distance (GSD)

The size of a single pixel as measured on the ground. This is also referred to as "resolution".

GSD

See Ground Sample Distance.

Image Support Data (ISD)

A set of files which contain all the necessary data necessary to use and process Imagery Products. These files can be viewed as a collection point for all ancillary data that is expected to be useful to a customer.

ISD

See Image Support Data.

JPEG2000 format

The JPEG2000 format is a JPEG format that was introduced in the year 2000. It has considerable advantages over basic JPEG format including error resilience and progressive transmission.

LE

Linear Error.

LE90

Linear Error at 90 percent confidence. Indicates that the actual elevation of an object is represented within the stated accuracy for at least 90% of elevation posts.

MBR

Minimum-bounding rectangle.

Metadata

Ancillary data that describes and defines the imagery product. DigitalGlobe provides metadata in a set of Image Support Data files.

Mosaic

The process of digitally assembling images to create contiguous large-area coverage.



MrSid format

Multi-Resolution Seamless Image Database. This format compresses large raster images while maintaining the image quality.

MS

See Multispectral.

Multispectral

Imagery with data recorded in multiple discrete spectral bands. Imagery collected in four or eight ranges of wavelengths in the electromagnetic spectrum.

Nadir

The point on the ground vertically beneath the sensor.

National Imagery Transmission Format

See NITF format.

Nearest Neighbor Interpolation

Uses the value of the closest point and disregards all other values, yielding a piecewise-constant interpolant.

NED

National Elevation Dataset DEM. NED DEM is available in the United States. Accuracy in Alaska is not as high as in the contiguous United States.

NIIRS

National Image Interpretability Rating Scale.

NIR1

Near Infrared 1.

NIR2

Near Infrared 2.

NITF format

National Imagery Transmission Format. A United States Department of Defense standard for transmitting and storing digital imagery.

NRG

Near-Infrared, Red, Green.

Off-nadir Angle

The angle between nadir and the point on the ground that the sensor is pointing. Off-nadir angle can be measured in the along-track (forward) direction or across-track (sideways) direction.

Orthorectification

The process of removing image distortions introduced by the collection geometry and variable terrain, and re-sampling the imagery to a specified map projection. Also referred to as ortho-correction or terrain correction.



Pan/Panchromatic

A wide spectral band which is comprised of reflected light in the visible spectrum (blue, green, red and NIR). It is displayed as a black and white image.

Pan-Sharpened

Processed used to colorize imagery by fusing multispectral and panchromatic bands.

Photogrammetry

The art, science, and technology of obtaining reliable information about physical objects and the environment through the process of recording, measuring, and interpreting photographic images and patterns of electromagnetic radiant imagery.

Pixel

Picture element. The smallest element comprising a digital image.

PNIIRS

Predicted National Image Interpretability Rating Scale.

Product Framing

The manner in which Imagery Products are delivered. Products are either Scene-based or Area-based.

PVL

Physical Volume Library.

QB02

QuickBird satellite.

Radiometric Correction

The correction of variations in data that are not caused by the object or scene being scanned, such as non-responsive detectors, scanner inconsistencies, and atmospheric interference.

Remote Sensing

The measurement or acquisition of data about an object by an instrument not in contact with the object. Satellite imagery, aerial photography, and radar are all types of remote sensing.

Resolution

The resampled image pixel size derived from GSD.

RGB

Red, Green, Blue.

RMSE

Root Mean Square Error.

RPC

Rational Polynomial Coefficient camera model. RPCs provide the camera geometry obtained at the time of the image collection.



Scale

The ratio of distance on a map as related to the true distance on the ground. Products with a larger scale have higher geometric accuracies than products with a smaller scale.

Seamlines

Seamlines are the lines at which two separate images overlap. These overlapping images can be blended along the seamline to show a more uniform image.

Sensor Azimuth

The azimuth of the sensor measured from the target.

Sensor Correction

The correction of variations in data that are caused by variations in sensor geometry, attitude, and ephemeris.

Spatial Mosaic

The assembly of multiple scenes, each of which shows a portion of the order polygon, into a single image. Usually involves edge matching adjacent scenes.

SRTM

Shuttle Radar Topography Mission digital elevation models.

Stereo

The collection of two or more images of the same Area of Interest (AOI) from different viewing angles.

Sun Azimuth

The azimuth of the sun as seen by an observer sitting on the target measured in a clockwise direction from north.

Sun Elevation

The angle of the sun above the horizon.

Sun-Synchronous

An orbit which rotates around the Earth at the same rate as the Earth rotates on its axis.

Swath Width

The width of an image.

Target Azimuth

The azimuth of the target as seen by an observer sitting on the spacecraft measured in a clockwise direction from north.

TDI

Time Delay Integration.

Terrain Correction

The correction for variations in data caused by terrain displacement due to off-nadir viewing.

TLC

Time-lagged Line Count.

Universal Transverse Mercator Geographic Coordinate System (UTM)

See UTM.



UTM

Universal Transverse Mercator Geographic Coordinate System. UTM utilizes a two-dimensional Cartesian system to specify locations on the Earth's surface.

WV01

WorldView-1 satellite.

WV02

WorldView-2 satellite.

WV03

WorldView-3 satellite.



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